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An acoustic model for automatic control of a slide flute

Brigitte d'Andréa-Novel, Benoît Fabre, Jean-Michel Coron

Abstract—In this paper, we consider the problem of modeling and control of a slide flute : a kind of recorder without finger holes but which is ended by a piston mechanism to modify the length of the resonator. A previous study has been done (see [3]), but with a very simple boundary condition for the mouth, corresponding to an ideal situation assuming that the acoustic pressure is zero at the entrance of the resonator.

In this work, we have taken into account a more realistic model, describing the coupling effects between the jet and the pipe. The jet is obtained by blowing through a flue channel and formed by flow separation at the flue exit, and finally directed towards a sharp edge, called the labium. The resulting structure can then be seen as a nonlinear oscillator coupled with the pipe which is a linear acoustic resonator. The pressure obtained through this model has been compared to the pressure measured on an actual instrument, a recorder closed at its end.

A modal analysis is then performed using the linearized boundary conditions which can also be used to compute the suitable blowing pressure and the suitable pipe length to obtain a desired fundamental frequency or equivalently a desired pitch. This will constitute the basis of our control algorithm.

A possible musical application of such a device is to build a flue instrument with a pitch independent of the dynamical level.

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I. INTRODUCTION

Slide flutes are mostly used for jazz and popular music, even if they sometimes appear in the classical orchestra in works like the opera by Maurice Ravel, *L'Enfant et les Sortilèges*. We are interested in this paper to model and control this kind of instrument made of a cylindrical stopped resonator similar to a stopped organ pipe and of a blowing mouthpiece analogous to that of a recorder. Contrary to flutes, organ pipes and recorders, the variation of the pitch is obtained through a piston mechanism. From a physical point of view, stopped pipes have not been studied so widely as open pipes. Moreover, moving boundary conditions introduce interesting problems also from a mathematical point of view.

In the case of open pipes, physical models for the excitation mechanism have been developed to produce quite realistic sound synthesis (see e.g. [8], [19]). In the present work, we use the same model of the excitator and couple it to a pipe model with moving boundary conditions. Even if the

resulting dynamical model can be used for sound synthesis purposes (as illustrated in section VII), our main goal is to develop control algorithms to automatically control such physical instruments. An important musical application for such device is to produce musical dynamics (*piano e forte*) at constant pitch by adjusting both the blowing pressure and the slide position.

The obtention of physical models for analysis and synthesis for flue musical instruments such as organs or recorders has been an important research subject for a few decades. We will not be exhaustive, but we can mention the paper by Cremer and Ising [7] giving a first quasi-stationary model of the jet drive, which has been later improved by many authors (see e.g. [6], [11]). The works of Howe [12] pointed out the importance of vortex shedding at the labium. In fact, in steady blowing conditions, models not taking into account this effect (e.g. in [11]) led to an overestimation of the amplitude of the pressure oscillation in the pipe (see for example [17]). Therefore, as in [20], we have taken into account these interactions jet/labium, but as already mentioned, the system we are studying is different : the resonator's length is time-varying, controlled through the piston mechanism and there is no finger hole (see Fig. 1). The whole structure can then be described by two linear Partial Differential Equations coupled with nonlinear Ordinary Differential Equations describing the boundary conditions :

- for the mouth, taking into account the jet dynamics,
- and for the piston.

In section II we recall our pipe model. In section III, we give the physical models of the jet channel and the mouth. In section IV we compute the boundary condition at the end of the resonator and at its entrance, taking into account the jet dynamics. In section V we present the modal analysis we have developed from the linearized boundary conditions, and we compute the different frequencies which are functions of the resonator's length and of the steady blowing pressure. It can be noticed that the frequencies are odd multiples of the fundamental one, as expected for open-closed pipes instruments like the pan flute or the clarinet. Conversely, if we want to obtain a reference fundamental frequency, we can use the previous linearized boundary conditions, where we fix the desired frequency value, to compute the suitable blowing pressure and the suitable length. This will constitute our control algorithm described in section VI. Finally in section VII we present our numerical scheme together with some simulation results. Let us point out that in our previous paper [4], simulation results showed that the resulting blowing pressure range was lower than in actual pipes. This was mainly due to the simplifications

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of the jet and source models (see also [5, Sec. 3]) which overestimated the jet amplification and sound production at low jet velocities. To solve this problem, we propose to implement a numerical filter to obtain a more realistic dynamics of the jet position in the mouth. The resulting pressure is compared with experimental data obtained from an actual instrument and we conclude.

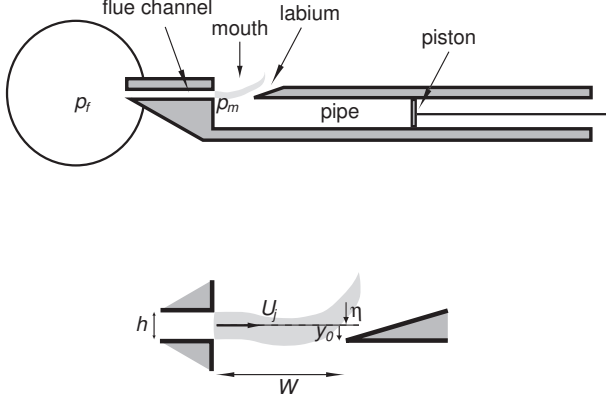


Fig. 1. The slide flute

II. PHYSICAL MODEL OF THE PIPE

If ρ_0 denotes the air density at rest, S_p the constant section of the pipe which is supposed to be cylindrical, and assuming the flow rate $u(x, t)$ at time t and point x in the pipe and the relative pressure $p(x, t) = P - P_{atm}$ (P_{atm} denoting the atmospheric pressure) are uniform on a section, the Euler equation, giving the fluid dynamical properties can be written :

$$\frac{\partial u}{\partial t} = -\frac{S_p}{\rho_0} \frac{\partial p}{\partial x} \quad (1)$$

neglecting the viscous and thermal effects near the walls.

The mass conservation law has the following form :

$$\frac{\partial \rho}{\partial t} = -\frac{\rho_0}{S_p} \frac{\partial u}{\partial x}. \quad (2)$$

Finally, assuming that the transformation is adiabatic, we have the following equation, c being the sound velocity in the fluid :

$$p = c^2 \rho \quad (3)$$

which allows to link the pressure fluctuations p and the density fluctuations ρ .

Then, replacing ρ from p in (2), we obtain the second state equation which completes (1), i.e. :

$$\frac{\partial p}{\partial t} = -\frac{\rho_0 c^2}{S_p} \frac{\partial u}{\partial x}. \quad (4)$$

Differentiating (4) with respect to t , (1) with respect to x and collecting the resulting equations lead to the d'Alembert equation :

$$\frac{\partial^2 p}{\partial t^2} - c^2 \frac{\partial^2 p}{\partial x^2} = 0. \quad (5)$$

Equations (1) and (4) allow one to write the system dynamics in the following state-space form with $Y = \begin{pmatrix} u \\ p \end{pmatrix}$:

$$\frac{\partial Y}{\partial t} + A \frac{\partial Y}{\partial x} = 0, \text{ with } A = \begin{pmatrix} 0 & S_p/\rho_0 \\ \rho_0 c^2/S_p & 0 \end{pmatrix}. \quad (6)$$

This representation can be diagonalized :

$$\partial_t \xi + \Lambda \partial_x \xi = 0, \text{ with } \Lambda = \begin{pmatrix} c & 0 \\ 0 & -c \end{pmatrix} \quad (7)$$

where the change of coordinates is given by :

$$\xi = \begin{pmatrix} \alpha \\ \beta \end{pmatrix} = \begin{pmatrix} u + \frac{S_p}{\rho_0 c} p \\ u - \frac{S_p}{\rho_0 c} p \end{pmatrix} \quad (8)$$

and

$$Y = \begin{pmatrix} u \\ p \end{pmatrix} = \begin{pmatrix} \frac{\alpha + \beta}{2} \\ \frac{\rho_0 c (\alpha - \beta)}{2 S_p} \end{pmatrix}. \quad (9)$$

The eigenvalues $c > 0$ and $-c < 0$ being respectively the velocity of the ingoing wave $\alpha(x, t)$ and of the outgoing wave $\beta(x, t)$. $\alpha(x, t)$ and $\beta(x, t)$ satisfy two classical wave equations :

$$\frac{\partial \alpha}{\partial t} + c \frac{\partial \alpha}{\partial x} = 0 \text{ and} \quad (10)$$

$$\frac{\partial \beta}{\partial t} - c \frac{\partial \beta}{\partial x} = 0. \quad (11)$$

The quantities $\frac{\partial \alpha}{\partial t} + c \frac{\partial \alpha}{\partial x}$ and $\frac{\partial \beta}{\partial t} - c \frac{\partial \beta}{\partial x}$ can be seen as the time derivatives $\frac{d\alpha}{dt}$ and $\frac{d\beta}{dt}$ of α and β in (x, t) along the solutions of :

$$\frac{dx}{dt} = c \text{ and } \frac{dx}{dt} = -c, \quad (12)$$

called “characteristic curves”. Since $\alpha(x, t)$ and $\beta(x, t)$ are constant along these curves, α and β are called the **Riemann invariants** (see e.g. [16, Tome II, Chap. 12]).

As it has been done in [2] in the case of an overhead crane with a **variable length flexible cable**, it is interesting to apply the following change of variable

$$x = L\sigma \quad (13)$$

to transform the system into one having a fixed spatial domain for σ , i.e. $\sigma \in [0, 1]$.

According to (13), if we denote :

$$\begin{cases} \tilde{\alpha}(\sigma, t) = \alpha(x, t) = \alpha(L(t)\sigma, t) \\ \tilde{\beta}(\sigma, t) = \beta(x, t) = \beta(L(t)\sigma, t) \end{cases} \quad (14)$$

equations (10) and (11) become :

$$\begin{cases} \frac{\partial \tilde{\alpha}}{\partial t}(\sigma, t) + \left(\frac{c - \dot{L}\sigma}{L} \right) \frac{\partial \tilde{\alpha}}{\partial \sigma}(\sigma, t) = 0 \\ \frac{\partial \tilde{\beta}}{\partial t}(\sigma, t) - \left(\frac{c + \dot{L}\sigma}{L} \right) \frac{\partial \tilde{\beta}}{\partial \sigma}(\sigma, t) = 0. \end{cases} \quad (15)$$

We still have two wave equations, but with time variable velocities depending on L and on the control variable \dot{L} , where \dot{L} denotes the time derivative of L .

Remark 1: The term due to the piston velocity, should be interpreted as acoustic source terms when placed at the right hand side of equation (15). Nevertheless, the velocity of the waves equations remain time dependent through L and the explicit expression of $\tilde{\alpha}$ and $\tilde{\beta}$ become rather complicated to derive through the associated characteristic equations and the boundary conditions.

III. PHYSICAL MODELS OF THE JET CHANNEL AND THE MOUTH

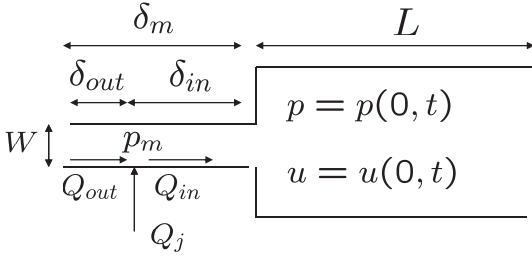


Fig. 2. The 1D model of the mouth

In [18], [20], [19], [9], the two-dimensional geometry of the mouth is modeled in a low frequency plane wave approximation by a one-dimensional representation, by an equivalent pipe segment of length δ_m (see Fig. 2) taking into account the constriction of the pipe at the blowing end.

In this one-dimensional representation, the flue exit, when the jet is formed, is located at an acoustic distance δ_{out} from the outside and δ_{in} from the entrance of the resonator.

At the flue exit, because the region is compact, one can apply the mass conservation law :

$$Q_j + Q_{out} = Q_{in} \quad (16)$$

where Q_j , Q_{out} and Q_{in} are respectively the jet flow, the flow in the portion δ_{out} and δ_{in} respectively, expressed in m^3/s .

The pressure p_m in the mouth at the flue exit can be related to the flow Q_{out} by the radiation impedance, which leads in the time domain to the following linear differential equation :

$$\begin{cases} p_m = c_2 \ddot{Q}_{out} - c_3 \dot{Q}_{out} \\ c_2 = \frac{\rho_0 r_m^2}{4c S_m} \text{ and } c_3 = \frac{\rho_0 \delta_{out}}{S_m} \end{cases} \quad (17)$$

where S_m is the mouth cross section at the flue exit, and r_m is the radius of a circle having the same mouth cross section, i.e. such that $\pi r_m^2 = S_m$.

Neglecting friction, the jet at the flue exit is governed by the Bernoulli equation :

$$\rho_0 l_c \frac{dU_j}{dt} + \frac{1}{2} \rho_0 U_j^2 = p_f - p_m \quad (18)$$

where U_j denotes the jet velocity in the flue channel, l_c the length of the channel, p_f denotes the excitation pressure at the entrance of the channel, generated by the player and p_m denotes the pressure in the mouth of the instrument (see Fig. 1).

Noticing that the flow continuity is assumed at the entrance of the resonator, that is : $Q_{in}(0) = u(x = 0, t) = u_0(t)$, the pressure $p(x = 0, t) = p_0(t)$ can also be related to the pressure p_m through momentum conservation :

$$\begin{cases} p_m - p_0 = c_1 \dot{u}_0 - \Delta p \\ c_1 = \frac{\rho \delta_{in}}{S_m} \end{cases} \quad (19)$$

where Δp represents the pressure jump across the pipe of length δ_{in} . This pressure jump, responsible for the sound production, can be mainly decomposed in two terms :

$$\Delta p = \Delta p_{jd} + \Delta p_a \quad (20)$$

Δp_{jd} denoting the pressure jump due to the jet drive mechanism and Δp_a the vortex shedding when the flow separates at the edge of the labium which appears to be determinant in limiting the amplitude of the oscillation during steady-state, but also to be important to describe nonlinear behavior in the transient attack.

The term Δp_{jd}

As explained for example in [20], [19], the pressure due to the jet-drive is determined by the time derivative of the flow source Q_1 corresponding to the portion of the jet flow entering the pipe at the labium :

$$\Delta p_{jd} = -\frac{\rho_0 \delta_d}{S_m} \frac{dQ_1}{dt} \quad (21)$$

where δ_d is the acoustic distance between the dipole sources Q_1 and Q_2 generated at the labium, in the one-dimensional representation of the instrument. Assuming the jet has a Bickley velocity profile (see e.g. [14]), denoting H the jet width, y_0 the labium position with respect to the flue exit axis (y being positive towards the interior of the pipe) the following expression is obtained :

$$Q_1 = bH\bar{U}_j \left[1 + \tanh \left(\frac{\eta - y_0}{b} \right) \right] \quad (22)$$

where b is a positive jet parameter characterizing the velocity profile at the flue exit, η denotes the jet position which will be detailed in the next paragraph and \bar{U}_j denotes the asymptotic value of the jet velocity depending on the excitation pressure p_f (see equation (18)), i.e. :

$$\bar{U}_j = \sqrt{2p_f/\rho_0}. \quad (23)$$

The term Δp_a

Using e.g. [10], [20], [19], one can express the vortex shedding term induced at the labium by the transverse acoustic flow of the pipe by the following expression :

$$\Delta p_a = -\frac{1}{2}\rho_0 \left(\frac{u_0}{\alpha_v S_m} \right)^2 \text{sign}(u_0) \quad (24)$$

where α_v is the vena-contracta factor of the flow. It can be seen that this term is dissipative, corresponding to the kinetic energy dissipation by turbulence of the jet, formed by separation of the acoustic flow at the labium.

Physical model of the jet position

Let us now give an expression of the jet position η in the mouth obtained from recent works e.g. [8], denoting h the jet height :

$$\eta(t) = 2 \frac{u_0(t - \tau_l)h}{\pi S_m U_j} e^{\mu W} \quad (25)$$

where μ denotes the spatial amplification of the jet, W the distance between the flue exit and the labium and the delay τ_l is given by :

$$\tau_l = \frac{W}{0.3U_j}. \quad (26)$$

We can see that the delay τ_l is time varying since it depends on U_j . But, in the transient regime of the jet velocity, U_j takes values near the origin, so that in numerical simulations, we have to wait $U_j \geq \gamma$ for a small positive value γ to consider equation (26). Before that, we take $\eta = 0$.

IV. BOUNDARY CONDITIONS

Let us now complete the pipe model (15) with the boundary conditions at $\sigma = 0$ (i.e. $x = 0$) and $\sigma = 1$ (i.e. $x = L$).

A. Boundary condition at the entrance of the resonator

Let us first consider the boundary condition at the entrance of the resonator. It can be obtained replacing p_m from equation (19) in equation (18), which leads to :

$$p_0(t) = p_f - \rho_0 l_c \frac{dU_j}{dt} - \frac{1}{2}\rho_0 U_j^2 - c_1 \dot{u}_0(t) + \Delta p. \quad (27)$$

This boundary condition can be rewritten in the α and β variables using (9) and in the $\tilde{\alpha}$ and $\tilde{\beta}$ variables, using (14) which gives finally :

$$\tilde{\alpha}(0, t) = \tilde{\beta}(0, t) + \frac{2S_p}{\rho_0 c} \left[p_f - \rho_0 l_c \frac{dU_j}{dt} - \frac{1}{2}\rho_0 U_j^2 - \frac{c_1}{2}(\dot{\tilde{\alpha}} + \dot{\tilde{\beta}})(0, t) + \Delta p \right] \quad (28)$$

Remark 2: In the previous paper [3], the boundary condition which was used was the very simple one $p(x = 0, t) = 0$, i.e. $\tilde{\alpha}(0, t) = \tilde{\beta}(0, t)$, corresponding to an ideal case. Taking into account the physical models of the jet and of the mouth leads to the more realistic above condition. It can be also noticed that $p_0(t)$ now depends on $\dot{u}_0(t)$ but using (20), (21), (22), (24) and (25) also on $u_0(t)$ and $\dot{u}_0(t - \tau_l)$.

Moreover, we need the value of U_j and its time-derivative to bring up to date the boundary condition (28). So we have to solve at each time instant, the ordinary differential equation describing the dynamical evolution of U_j . This equation is obtained from (18) where we replace p_m by its expression (17) and using equation (16) which becomes at $x = 0$:

$$Q_{out} = Q_{in} - Q_j = u_0(t) - S_e U_j \quad (29)$$

S_e denoting the cross section of the channel at the flue exit.

Finally, the equation giving the value of $U_j(t)$ can be written :

$$c_2 S_e \ddot{U}_j - (\rho_0 l_c + c_3 S_e) \dot{U}_j + c_3 \dot{u}_0 - c_2 \ddot{u}_0 = \frac{1}{2}\rho_0 U_j^2 - p_f. \quad (30)$$

When taking realistic numerical values of the constants involved in (30) it can be seen that $c_2 S_e \simeq 10^{-9}$, which is negligible with respect to the multiplying factor of \ddot{U}_j . Therefore, using singular perturbation arguments, one can neglect the terms in \ddot{U}_j in (30) and we can consider the following equation which will be used to evaluate U_j and its time derivative :

$$(\rho_0 l_c + c_3 S_e) \dot{U}_j = p_f - \frac{1}{2}\rho_0 U_j^2 + c_3 \dot{u}_0 - c_2 \ddot{u}_0. \quad (31)$$

Finally, the boundary condition at the entrance of the resonator consists in the two equations (28) and (31) at $x = 0$.

B. Boundary condition at the end of the resonator

Considering the piston mechanism which allows the translation of the slide flute, the boundary condition at the end of the flute, can be written as a first approximation neglecting friction terms :

$$S_p p(L, t) + F = m \ddot{L} \quad (32)$$

F being the force exerted by the motor on the slide and m the piston mass.

In a first step, one can consider that the control variable is the piston velocity \dot{L} , linked to the physical control F homogeneous to \ddot{L} , via the integrator (or cascade) system given by (32). Then if \dot{L} is known, one can then compute the physical control F to apply, using e.g. “backstepping” techniques (see [1]). One can therefore consider, without loss of generality, the following boundary condition at $x = L$:

$$u(L, t) = S_p \dot{L} \quad (33)$$

which can be rewritten in the $\tilde{\alpha}$ and $\tilde{\beta}$ variables, using (9) and (14) :

$$\tilde{\alpha}(1, t) + \tilde{\beta}(1, t) = 2S_p \dot{L}. \quad (34)$$

V. MODAL ANALYSIS OF THE LINEARIZED BOUNDARY CONDITIONS

To compute the natural modes of the system, we have to keep only linear terms in the boundary conditions obtained in the previous section. More precisely, we approximate \tanh by its argument in (22) for the expression of Δp_{jd} and we neglect the nonlinear term Δp_a given by (24). Writing U_j , $\tilde{\alpha}$ and $\tilde{\beta}$ on the following form, where \bar{U}_j is the steady state value of the jet velocity (see equation (23)) :

$$\begin{cases} U_j = \bar{U}_j + U e^{i\omega t} \\ \tilde{\alpha}(x, t) = a e^{i\omega t} e^{-i\omega x/c} \\ \tilde{\beta}(x, t) = b e^{i\omega t} e^{i\omega x/c} \end{cases} \quad (35)$$

replacing U_j , $\tilde{\alpha}$ and $\tilde{\beta}$ in (28) and (31) at $x = 0$ and (34) at $x = L$ and keeping only linear terms, we have to solve an homogeneous linear system of 3 equations with 3 complex unknowns (U, a, b) of the form, where denoting $\kappa(\omega) = (c_1 + \bar{K} e^{-i\omega \tau_i})$:

$$A(\omega) \begin{pmatrix} a \\ b \\ U \end{pmatrix} = 0, \text{ with } A(\omega) = \begin{pmatrix} Z_c + \kappa(\omega) & -Z_c + \kappa(\omega) & 2\rho_0(\bar{U}_j + i\omega l_c) \\ c_3 i\omega + c_2 \omega^2 & c_3 i\omega + c_2 \omega^2 & -2(\rho_0 \bar{U}_j + i\omega c_0) \\ e^{-i\omega L/c} & e^{i\omega L/c} & 0 \end{pmatrix} \quad (36)$$

where the constants c_1 , c_2 and c_3 are given by (19) and (17), the characteristic impedance Z_c is given by :

$$Z_c = \frac{\rho_0 c}{S_p}, \quad (37)$$

and the constant \bar{K} is obtained by linearizing Δp_{jd} , the pressure jump due to the jet-drive (see equations (21), (22) and (25)). In fact, after some computations, we obtain the linearized expression $\Delta \bar{p}_{jd}$:

$$\begin{cases} \Delta \bar{p}_{jd} = \bar{K} \dot{u}_0(t - \tau_i) \\ \bar{K} = \frac{2\rho_0 \delta_d h e^{\mu W} H}{\pi S_m^2} (1 - y_0^2/b^2). \end{cases} \quad (38)$$

Therefore, to obtain a non trivial solution, the complex modes $\omega = \lambda + i\epsilon$ must satisfy :

$$\det(A(\omega)) = 0, \quad (39)$$

namely, the real numbers λ and ϵ must be solutions of the two real equations :

$$\begin{cases} \operatorname{Re}(\det(A(\lambda, \epsilon))) = 0 \\ \operatorname{Im}(\det(A(\lambda, \epsilon))) = 0. \end{cases} \quad (40)$$

In Fig. 3, we can see the 2D-surfaces $\operatorname{Re}(\det(A(\lambda, \epsilon))) = 0$ and $\operatorname{Im}(\det(A(\lambda, \epsilon))) = 0$ parameterized by λ and ϵ .

For $L = 0.265 \text{ m}$ and $p_f = 300 \text{ Pa}$, the three first frequencies f_{ic} , $i = 1, 2, 3$, corresponding to the three first modes $\lambda_{ic} = 2\pi f_{ic}$, $i = 1, 2, 3$ are approximately, in Hz :

$$f_{1c} \simeq 290.8, f_{2c} \simeq 903.7, f_{3c} \simeq 1474. \quad (41)$$

The corresponding values of ϵ_{ic} are, in s^{-1} :

$$\epsilon_{1c} \simeq 36.9, \epsilon_{2c} \simeq -24.2, \epsilon_{3c} \simeq -74.7. \quad (42)$$

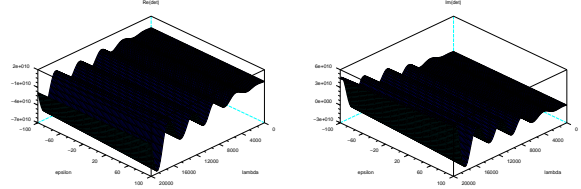


Fig. 3. $\operatorname{Re}(\det(A))$ and $\operatorname{Im}(\det(A))$ with respect to λ and ϵ

It can be noticed that :

$$\frac{f_{2c}}{f_{1c}} \simeq 3.11, \frac{f_{3c}}{f_{1c}} \simeq 5.07 \quad (43)$$

i.e. the frequencies of the modes are close to odd multiples of the first mode frequency, as expected for a closed-open pipe. For negative values of ϵ , the modes are oscillating corresponding to a time growth. Since they are solutions of the linearized problem, the modes calculated here can predict the oscillating frequency during transient state, at low amplitude. After this initial period, the saturation mechanisms may be responsible for a bifurcation in the system.

VI. AUTOMATIC CONTROL OF THE FLUTE

To realize an automatic control law, we have to compute p_f and L or equivalently, the pair (\bar{U}_j, L) such that a desired reference mode $\omega_r = \lambda_r + i\epsilon_r$ (or a desired reference frequency $f_r = \frac{\lambda_r}{2\pi}$) is obtained. Therefore, the control algorithm can be summarized as follows :

- λ_r and ϵ_r being chosen, solve the two equations (40) with respect to the unknown variables \bar{U}_{jr} and L_r , using for example a Newton algorithm.
- The resulting asymptotic jet velocity \bar{U}_{jr} will be reached through the servo-valve, asking for a desired steady-state pressure $p_{fr} = \frac{1}{2}\rho_0 \bar{U}_{jr}^2$.
- The resulting length of the pipe L_r will be reached, applying the following simple linear control law on the piston :

$$\dot{L} = -k(L - L_r), k > 0. \quad (44)$$

For example, to have $\omega_r = 2039$, corresponding to $f_r = f_{ideal} = c/4L = 324 \text{ Hz}$, solving equations (40) with initial conditions close to the first mode frequency leads to : $(\bar{U}_{jr} = 8.61 \text{ m/s}; L_r = 0.242)$ (or equivalently $(p_{fr} = 44.5 \text{ Pa}; L_r = 0.242)$).

VII. NUMERICAL SCHEME, SIMULATION RESULTS AND CONCLUSION

The numerical model which will be used for simulation and control is obtained by (15) together with the boundary conditions (28), (34) and (31). Since the velocities are respectively positive and negative for $\tilde{\alpha}$ and $\tilde{\beta}$, it was natural to implement a first-order un-centered upper scheme for $\tilde{\alpha}$ and down scheme for $\tilde{\beta}$. Numerical diffusion terms should be added to use centered schemes (see e.g. [15]).

To be more realistic and take into account viscous and thermal losses in the tube, we have also added a small friction term of the form νu in Euler equation (1), ν being a small friction coefficient. More accurate models exist for visco-thermal damping using non integer time derivative of the flow rate (see e.g. [13]).

In Fig. 4 and 5, we can observe two spectrograms of the simulated pressure. For comparison, the set point blowing pressure used in the simulation is the one measured on the experimental setup described below for pressures close respectively to $55 Pa$ and $245 Pa$.

The spectrogram of the pressure at $x = 0$ in Fig. 5 when $p_f \simeq 245 Pa$ shows that the oscillation takes place on the second acoustic mode of the pipe $f_{2s} \simeq 925 Hz$ which is very close to the computed values f_{2c} given in (41). For lower values of the blowing pressure, for example $p_f = 55 Pa$ in Fig. 4, simulations show an oscillation on the first pipe mode around $310 Hz$ also close to f_{1c} given in (41). The slight difference is probably due to the fact that the computed frequencies f_{ic} are obtained through **linearized** boundary conditions. Nevertheless, equations (40) constitute a good approximation to compute L_r as explained in section VI.

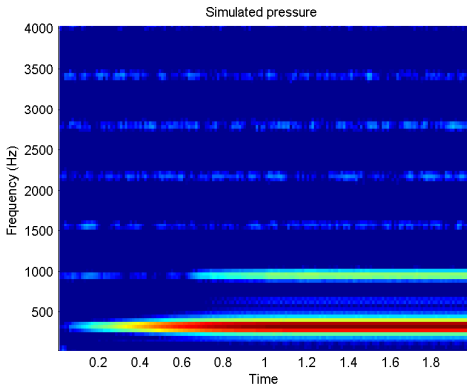


Fig. 4. Spectrogram of the simulated pressure using the experimental blowing pressure of Fig. 6 (close to $55 Pa$) and $L = 0.265 m$

The resulting pressure is now compared with experimental data obtained from an actual instrument. This instrument is built on a $18.4 mm$ diameter tube, associated with a recorder-like mouth piece. The tube is closed at its passive end. The total length of the pipe is $265 mm$. The window shows lateral walls of about $4 mm$ which act as ears in an organ pipe, increasing the end correction associated with radiation. The attack transient is generated by a pressure rise time of about $40 ms$ and shows an overshoot. The acoustic pressure in the instrument is measured at $16 mm$ of the block of the flute. From Fig. 6 and 7, one can observe that the oscillation regimes for $p_f \simeq 55 Pa$ and $p_f \simeq 245 Pa$ are the same as in the simulated cases (see Fig. 4 and 5). In the case $p_f \simeq 55 Pa$, the experimental spectrum during steady state is

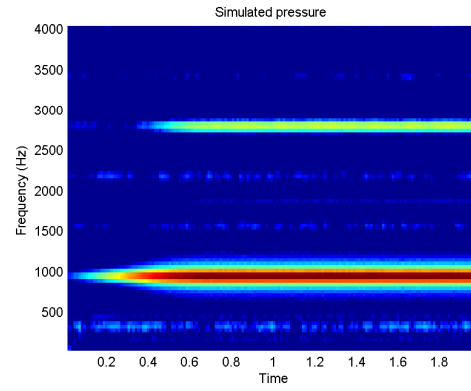


Fig. 5. Spectrogram of the simulated pressure using a higher experimental blowing pressure of Fig. 7 (close to $245 Pa$) and $L = 0.265 m$

dominated by harmonics 1 and 3 whereas the even harmonics appear weakly. These even harmonics are generated by nonlinear source terms (see equations (22)-(24)). They are weak compared to odd harmonics because they do not benefit of pipe resonances. For all flute-type instruments, increasing the blowing pressure results in a transition to an upper mode. In the case of a stopped pipe, the second mode is approximately at frequency 3 times higher than the first mode. Therefore, as expected in the case of overblowing pressure $p_f \simeq 245 Pa$, the oscillating regime is given by the second mode, both in experimental and simulated cases. The experimental pressure also shows noise modulated by the passive resonances of the pipe. This noise is generated by turbulence as discussed in [18]. This phenomenon has not been taken into account in our simulation model.

During the steady-state part of the oscillation, the simulation and experimental pressure signals show some similarities but also some differences. The oscillation regime is the same for simulated and measured systems : oscillation on the first pipe mode for $p_f \simeq 55 Pa$ and oscillation on the second pipe mode for $p_f \simeq 245 Pa$. The main differences are due to the fact that the experimental flute presents inharmonicity that the simulated one does not include. This is due to the dispersion associated with viscous and thermal effects at the pipe walls, which have not been included in our model, and also to the fact that the frequency dependence of the end corrections has not been modeled. The amplitude of the even harmonics appears to be relatively higher in the experimental data than in the simulation. This can be interpreted in terms of the simplification of the non-linear source terms in the model but also of the turbulent sound production already discussed.

Moreover, we can observe on Fig. 8 that the amplitude of the pressure oscillation predicted by the simulation is close to the one observed in the experimental data. This indicates that the dissipation model is quite efficient despite its simplicity.

The oscillation starts more slowly in the simulated flute than in the experimental one. Indeed the jet and source model

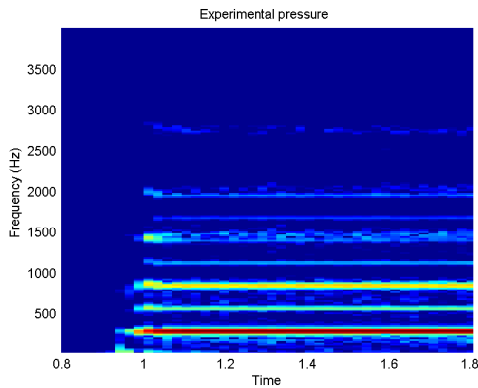


Fig. 6. Spectrogram of the experimental pressure with p_f close to 55 Pa and $L = 0.265$ m

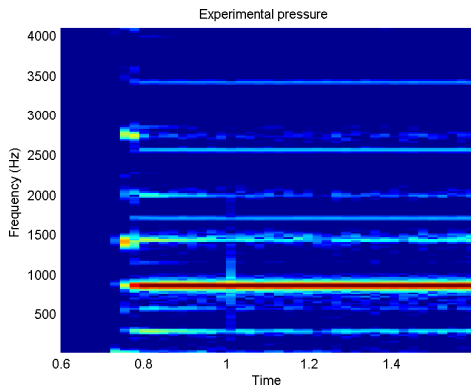


Fig. 7. Spectrogram of the experimental pressure with p_f close to 245 Pa and $L = 0.265$ m

we use are based on the analysis of steady-state oscillations. Some aspects of the starting transient are not yet well described by such models, as discussed in [9]. Moreover, these models have been elaborated for open recorder-like instruments and should be adapted in the case of a stopped pipe, but this work is out of the scope of the present paper.

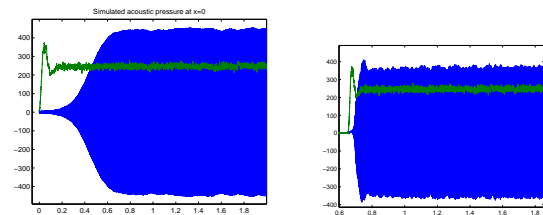


Fig. 8. Comparison between the model pressure and the experimental pressure with the same excitation blowing pressure $p_f \simeq 245$ Pa

As we have already said in the introduction, the blowing pressure range obtained for example in [4] or [5, Sec. 3] was lower than in actual pipes. This is mainly due to the simplifications of the jet and source models (eqs. (25), (26) and (21)) which overestimate the jet amplification and sound

production at low jet velocities. To solve this problem, we have implemented a numerical first order low pass filter on the jet position η leading to η_f to obtain a more realistic dynamics of the jet position in the mouth :

$$\eta_f(k+1) = c_4 \eta_f(k) + (1 - c_4) \eta(k), \quad c_4 \in [0; 1[. \quad (45)$$

Finally, Fig. 9 displays the simulation results we obtain when the player wants to produce scales by sliding the piston. It can be seen that the transient time response is about 0.1 s which is coherent with the attack transient time observed when the slide is fixed. The spectrogram shows the frequency shift resulting from the piston sliding.

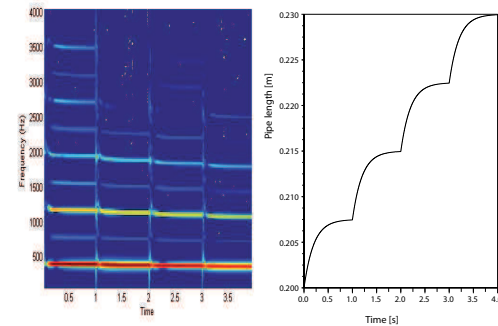


Fig. 9. A down scale : on the left spectrogram of the acoustic pressure ; on the right evolution of L from 0.20 m to 0.23 m

To conclude, the model presented in this paper produces satisfying simulation results and could be used for sound synthesis. Concerning the control, it must be noticed that the $(p_f; L)$ solution to reach a target pitch is not unique. Indeed, the slide flute can play the same pitch with a soft blowing and a short slide position, or with an increased blowing pressure and a longer slide position. The instrument therefore can produce musical dynamics (*piano e forte*) at constant pitch by adjusting both the blowing pressure and the slide position. The $(p_f; L)$ solution presented at the end of section VI corresponds to the closest solution to the L value for passive resonance.

An experimental prototype is under development at “Mines ParisTech” as shown in Fig. 10. The reference values $(p_{f_r}; L_r)$ have been obtained from the modal analysis performed on the linearized boundary conditions. For musical

applications, the target is defined as a pitch rather than a length. Consequently, it is more natural to regulate the frequency error and this necessitates to implement a real-time frequency detection to elaborate the closed-loop control.

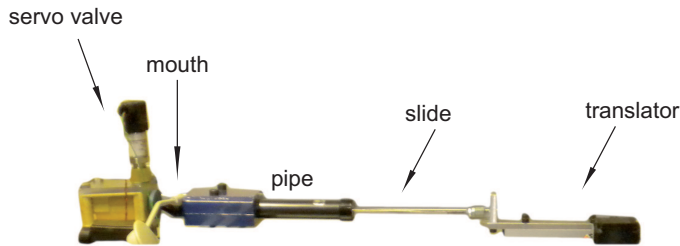


Fig. 10. The slide flute prototype

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